Amendments to the Claims:

This listing of the claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1-10   **(Cancelled).**

11.   **(Currently Amended)** A surveillance system comprising:

a plurality of cameras including at least two rotating cameras configured to perform a tracking/shooting function and a wide angle shooting function;

intruding object recognizing means for identifying a coordinate information of an object of monitoring on a coordinate space by analyzing image signals entered from said cameras;

camera function determining means ~~for allocating,~~ which when an information that there is an intruding object is obtained from said intruding object recognizing means, allocates, according to the coordinate information of an object of monitoring on a coordinate space, to a first camera said tracking/shooting function whose field of view is a predetermined direction of said object of monitoring and to a second camera a wide angle shooting function~~;~~, and further, the camera function determining means, when an information that there is no intruding object is obtained from said intruding object recognizing means, allocates to a plurality of cameras a wide angle shooting function; and

camera control means for controlling said plurality of cameras according to the allocation of functions by the camera function determining means.

12. **(Previously presented)** The surveillance system according to Claim 11, further provided with image accumulating means for accumulating images of the object of monitoring in advance and image recognizing means for comparing said accumulated images of the object of monitoring with an image of the object of monitoring entered from the first camera, wherein the camera function determining means allocate to a third camera a tracking function according to a result of comparison by said image recognizing means and the coordinate information of the object of monitoring on a coordinate space.

13. **(Previously presented)** The surveillance system according to Claim 11, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate a tracking/shooting function to the cameras in a preferential order with priority assigned to a camera nearest said object of monitoring.

14. **(Previously presented)** The surveillance system according to Claim 11, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate the tracking/shooting function to the cameras in a preferential order with priority assigned to a camera farthest from said object of monitoring.

15. **(Previously presented)** The surveillance system according to Claim 11, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate the wide angle shooting

function to the cameras in a preferential order with priority assigned to the camera farthest from said object of monitoring.

16. **(Previously presented)** The surveillance system according to Claim 12, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate a tracking/shooting function to the cameras in a preferential order with priority assigned to a camera nearest said object of monitoring.

17. **(Previously presented)** The surveillance system according to Claim 12, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate the tracking/shooting function to the cameras in a preferential order with priority assigned to a camera farthest from said object of monitoring.

18. **(Previously presented)** The surveillance system according to Claim 12, wherein the camera function determining means choose a camera whose field of view is in the predetermined direction of the object of monitoring, and allocate the wide angle shooting function to the cameras in a preferential order with priority assigned to the camera farthest from said object of monitoring.

19. **(Previously presented)** The surveillance system according to any one of Claims 11-18, wherein the camera function determining means memorize states of the plurality of cameras, and allocate the tracking/shooting function or the wide angle shooting function to

said plurality of cameras according to the states of said plurality of cameras and the coordinate

information of the object of monitoring on a coordinate space.

20.   **(Previously Presented)** The surveillance system according to Claim 19,

wherein the camera function determining means, when any camera is added or removed or any

camera is in trouble, update memorized states of the plurality of cameras.

21.   **(Previously Presented)** The surveillance system according to any one of

Claims 11-18, wherein the camera function determining means memorize a state of a monitored

area, and allocate the tracking/shooting function or the wide angle shooting function to the

cameras according to the state of said monitored area and the coordinate information of the

object of monitoring on a coordinate space.

22.   **(Previously Presented)** The surveillance system according to Claim 21,

wherein the camera function determining means, when any obstacle in the monitored area

prevents shooting of the object of monitoring, update the memorized states of the plurality of

cameras.

23.   **(Previously Presented)** The surveillance system according to Claim 12,

wherein the image accumulating means hold in advance facial image data picked up in many

different directions, and the image recognizing means compare said facial image data with a

facial image of the object of monitoring entered from any camera.